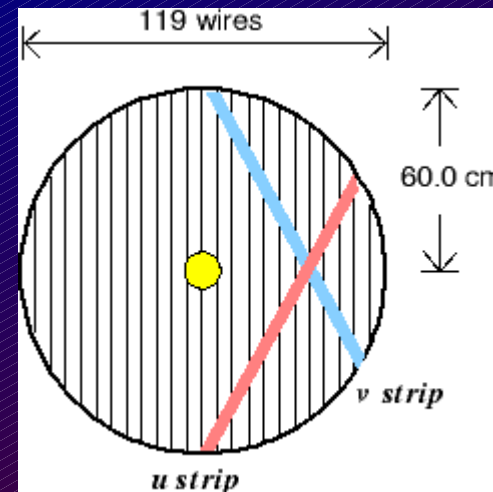
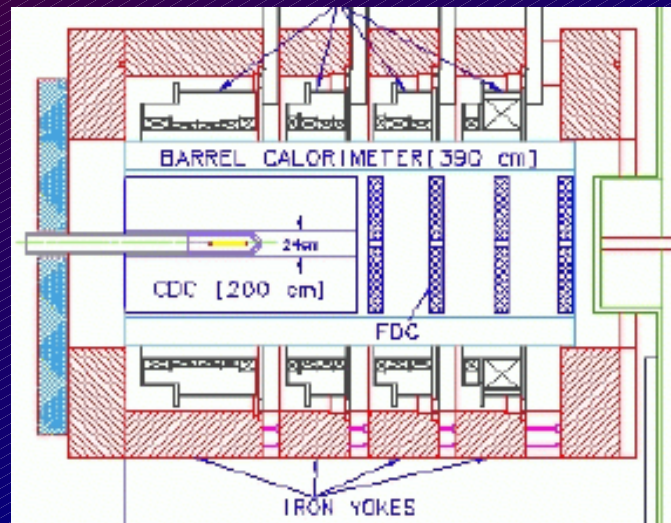


# FDC Status

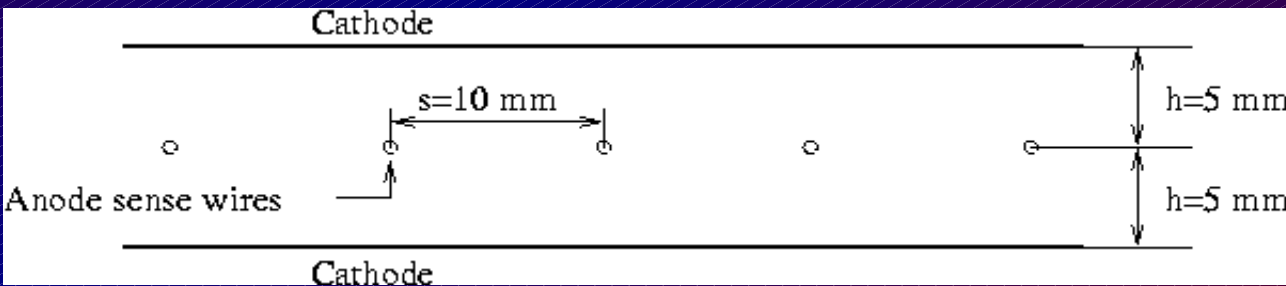
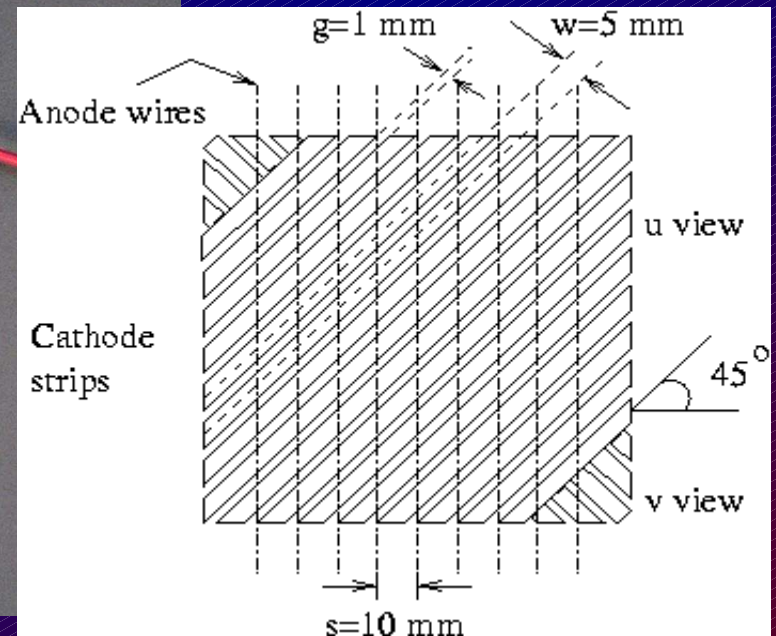
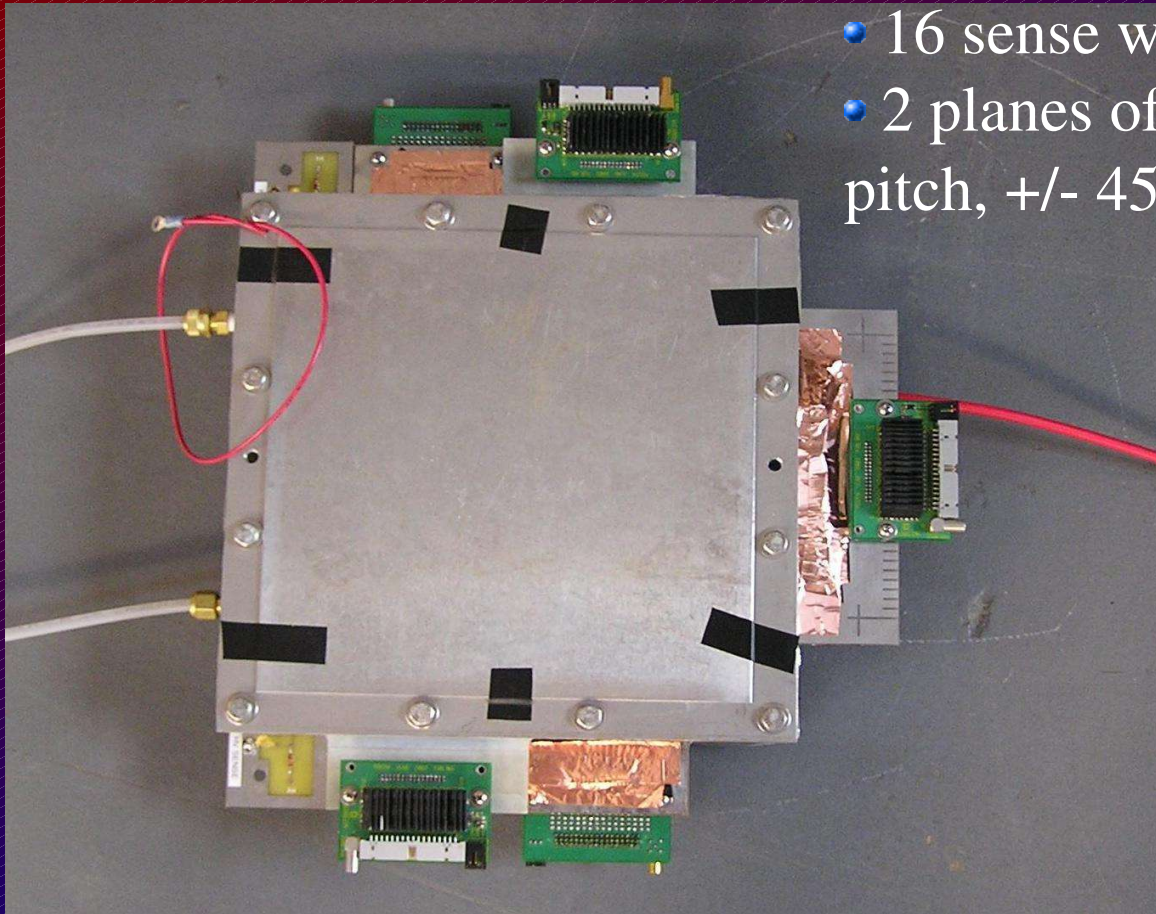
Simon Taylor  
Ohio University



GlueX Electronics Meeting, April 6-7, 2006.

# FDC prototype

- 16 sense wires with 10 mm pitch
- 2 planes of 32 cathode strips with 5 mm pitch,  $\pm 45^\circ$  with respect to the wires

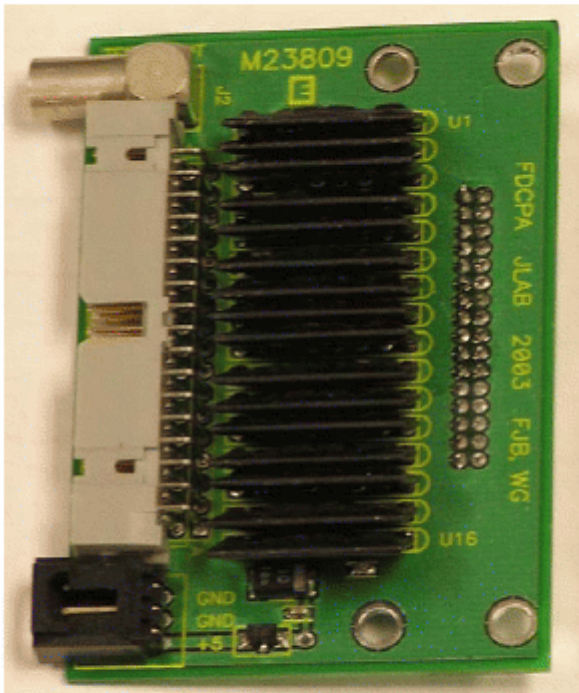


Goal: measure space point with  $<150\ \mu\text{m}$  resolution in each coordinate

Standard configuration in literature: no field wires...

# FDC Pre-amp boards

## HALL B SIP PREAMPS



- **Preamplifier properties:**

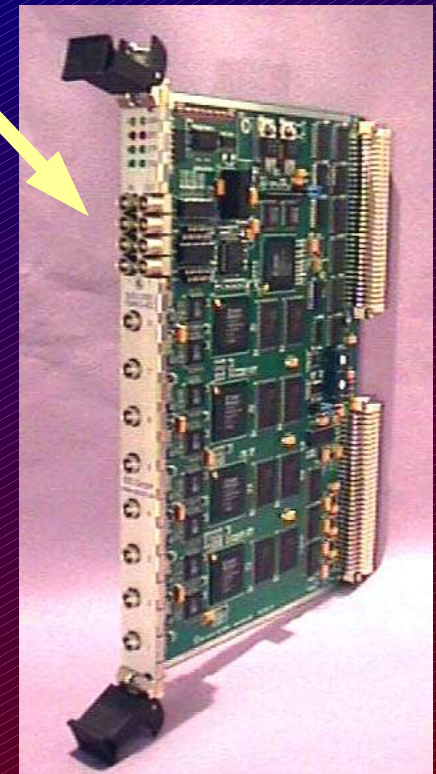
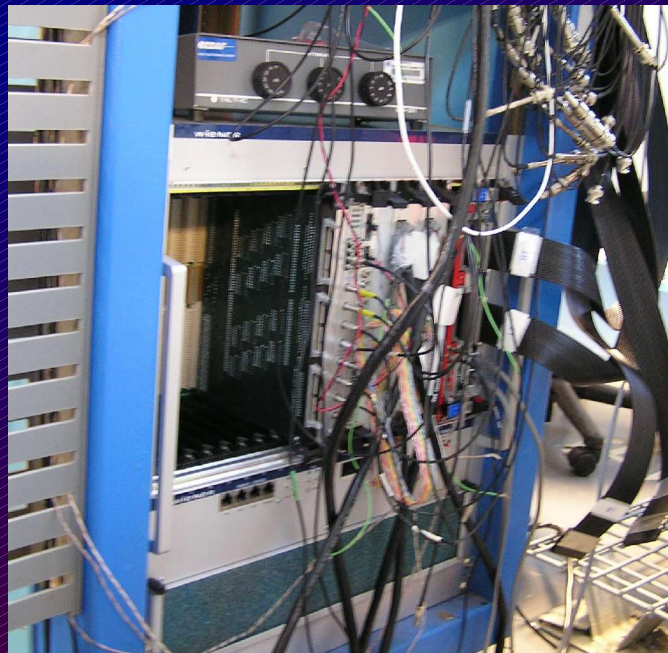
- *Gain 2.25 mV/ $\mu$ A*
- *fast rise and fall time (3–4 ns)*
- *wide frequency bandwidth*
- *wide dynamic range*
- *low noise*
- *low power dissipation (65 mW)*

- **SIP performance will be used as a benchmark for performance comparisons.**

**Presently cathode and anode amplifier boards are identical except for cathode polarity inversion.**

# FDC daq

- Readout hardware completely in VME
  - Cathode signals integrated using CAEN V792 (charge-integrating) ADCs
  - FDC anode wire timing signals and test stand chamber signals digitized using F1 TDC modules
  - 7 cathode signals + 1 anode wire read out with **Struck SIS3300 FADC**
    - 8 channels @ **105 MHz** per channel
    - (1 MHz - 105 MHz configurable)
    - 2 banks x 128K samples/channel memory
    - **0 ↔ -1 V** input range



# Cathode Charge Distribution

- Semi-empirical formula due to Gatti, et al./Mathieson & Gordon:

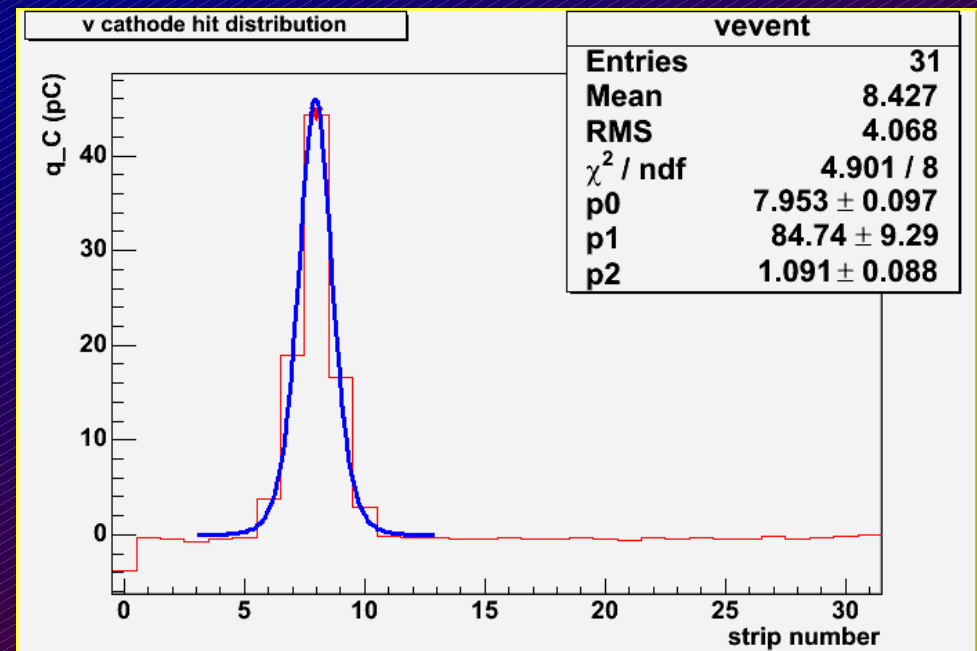
$$\frac{\rho(\lambda)}{q_a} = k_1 \left( \frac{1 - \tanh^2(k_2\lambda)}{1 + k_3 \tanh^2(k_2\lambda)} \right),$$

$k_1, k_2, k_3$  are empirical constants

$\lambda$  = normalized coordinate in cathode plane

- Prototype geometry:  $k_3 \rightarrow 0, k_1 \rightarrow k_2/4, k_2 \approx 1$

$$\frac{\rho(\lambda)}{q_a} = \frac{k_2}{4} \left( 1 - \tanh^2(k_2\lambda) \right)$$



# Newton-Raphson method I

Goal: Given distribution of charge over several adjacent strips, find the centroid position.

Wish to solve the following set of equations for  $\vec{x} = \{q_a, K_2, x_p\}$  :

$$F_i = Q_i - \frac{q_a}{4} \left[ \tanh \left( K_2 \left( \frac{x_p - x_i + a}{h} \right) \right) - \tanh \left( K_2 \left( \frac{x_p - x_i - a}{h} \right) \right) \right] = 0, \quad i = 1..3.$$

Taylor Expansion:

$$F_i(\vec{x} + \delta\vec{x}) = F_i(\vec{x}) + \sum_{j=1}^3 \frac{\partial F_i}{\partial x_j} \delta x_j + \mathcal{O}(\delta\vec{x}^2).$$

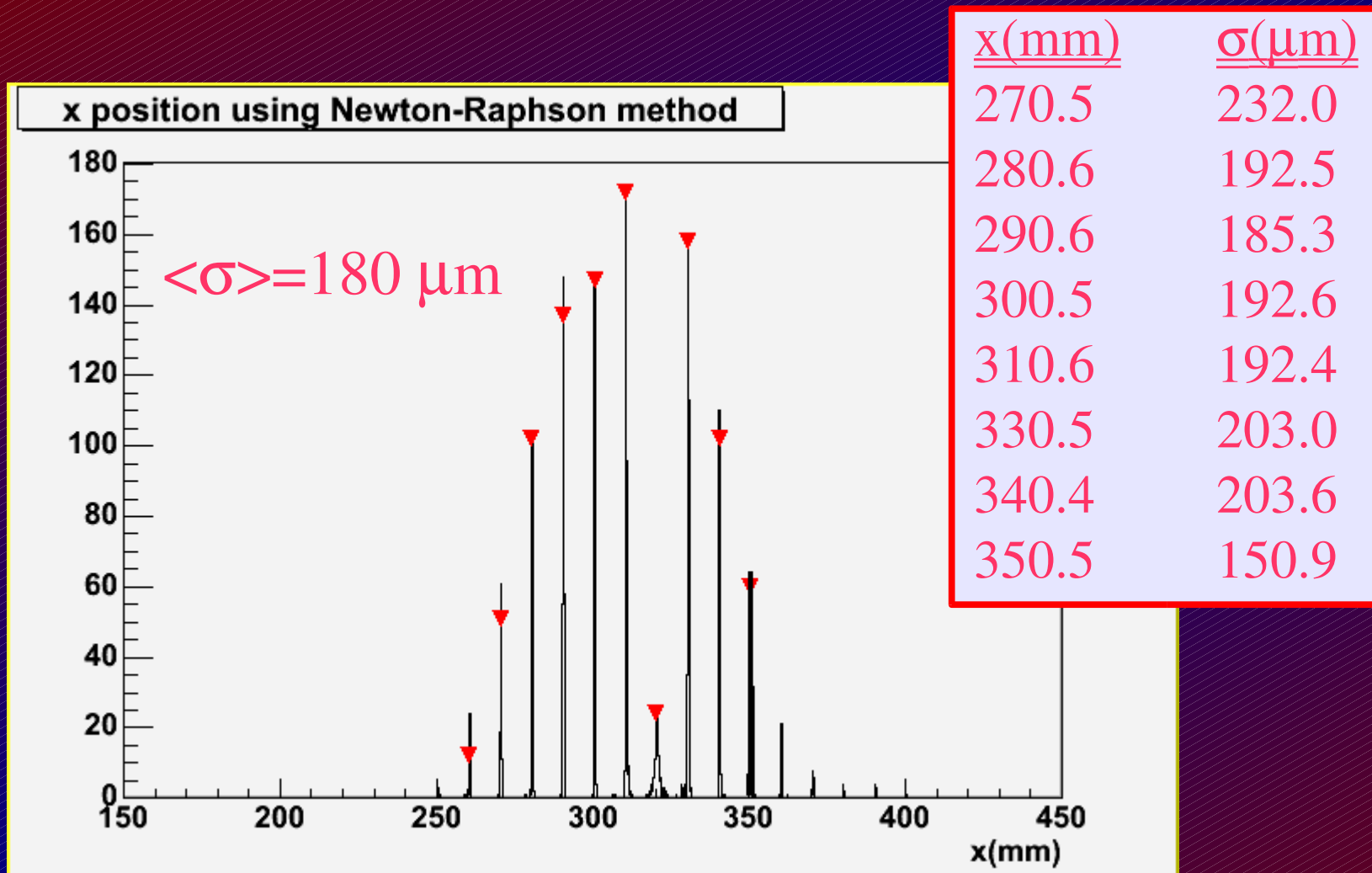
Estimate for correction:

$$\delta\vec{x} = -J^{-1}\vec{F},$$
$$J_{ij} \equiv \frac{\partial F_i}{\partial x_j}.$$

Iterate until

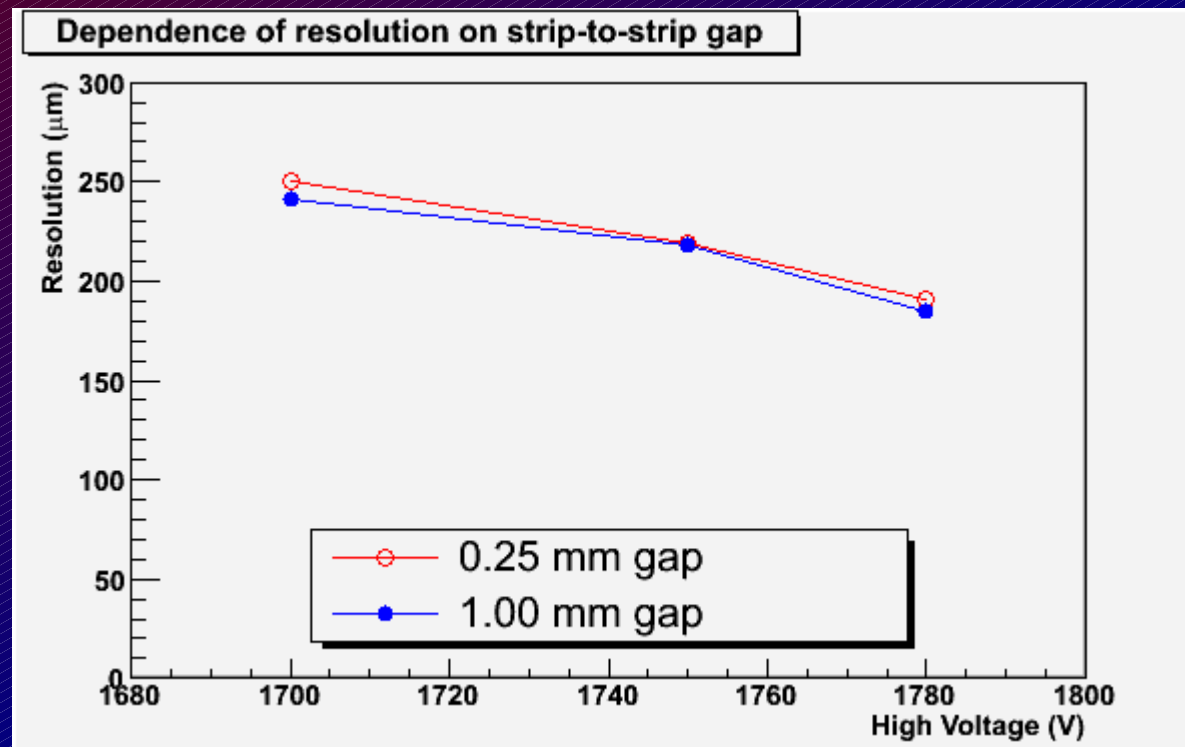
$$\sum_{j=1}^3 |\delta x_j| < \delta x_{min} = 0.0001 \quad \text{or} \quad \sum_{i=1}^3 |F_i| < F_{min} = 0.0001.$$

# Best results at $V_a = 1750$ V, 0.25 mm gap



(CAEN charge-integrating ADC readout, 1 anode wire/event)

# Comparison between 0.25 mm and 1 mm strip-to-strip gap widths



- Comparison was done with no cut on number of anode wires
- No significant difference in position resolution between two sets of measurements...



# Extracting Charge from FADC data

Simple method: unweighted sum over bin contents.

$$\int_{x_1}^{x_N} f(x) dx = h \sum_{i=1}^N f_i,$$

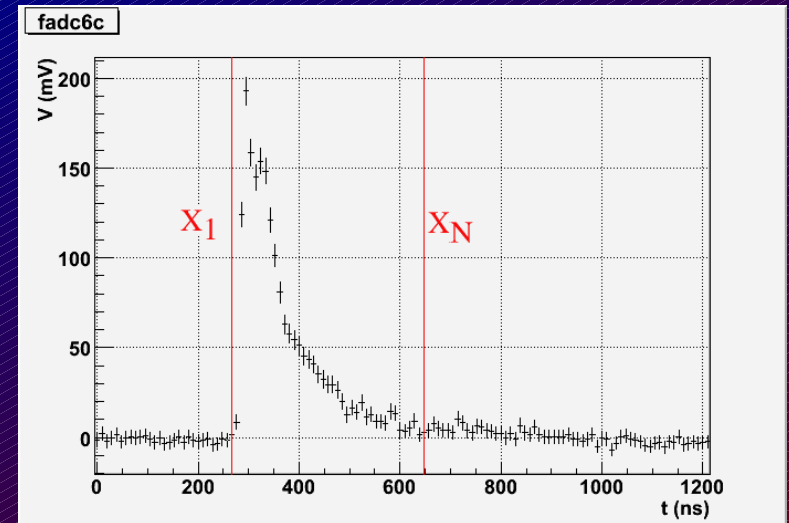
where  $h$  = bin size and  $f_i$  = bin contents

- Lower bound ( $x_1$ ) for integration:
  - Look for rising edge above threshold  $T$ .

$$f_2 - f_1 > \sqrt{\delta f_2^2 + \delta f_1^2}, \quad f_2 > T.$$

- Upper bound ( $x_N$ ) for integration:
  - Look for first region in tail (above peak) consistent with zero.

$$f_{N-1} < \delta f_{N-1}, \quad f_N < \delta f_N$$



# Extended Simpson's Rule

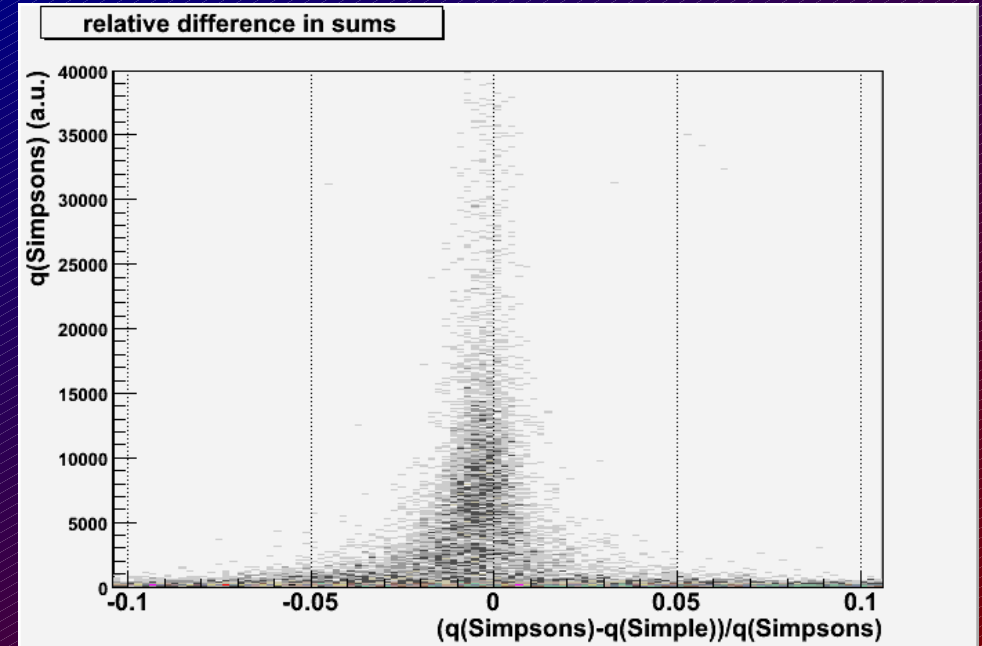
Method for integrating a function known at discrete points.

$$\int_{x_1}^{x_N} f(x) dx = h \left[ \frac{1}{3} f_1 + \frac{4}{3} f_2 + \frac{2}{3} f_3 + \frac{4}{3} f_4 + \cdots + \frac{2}{3} f_{N-2} + \frac{4}{3} f_{N-1} + \frac{1}{3} f_N \right] + \mathcal{O} \left( \frac{1}{N^4} \right),$$

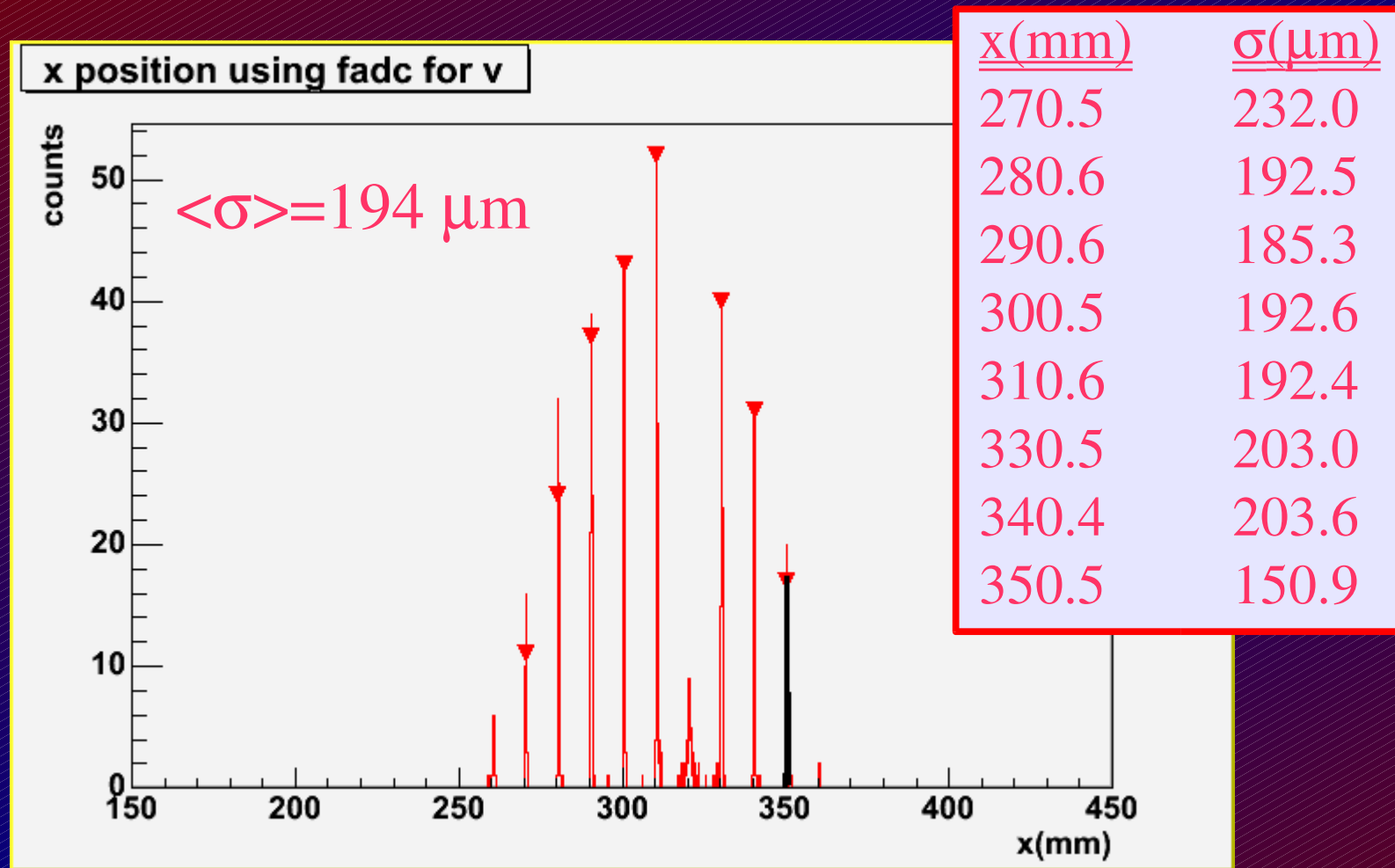
where  $h$  is the interval between points, and  $f_i = f(x_i)$ .

Comparison of 2 methods:

**Simple method** systematically **overestimates** integral relative to Simpson's method by about **0.36%** on average (from FDC test data)



# Position resolution using FADC data



- Newton-Raphson method used for both views
- Result worse than previous case by about  $14\ \mu\text{m}$

# Summary

- Average wire position resolution using CAEN ADCs ~ **180  $\mu\text{m}$**  for  $V_a = 1750 \text{ V}$
- No significant difference between 0.25 mm and 1.0 mm gap results
- Resolution using FADC still slightly worse than using charge-integrating ADCs

# FADC Timing Algorithms

Simon Taylor  
Ohio University

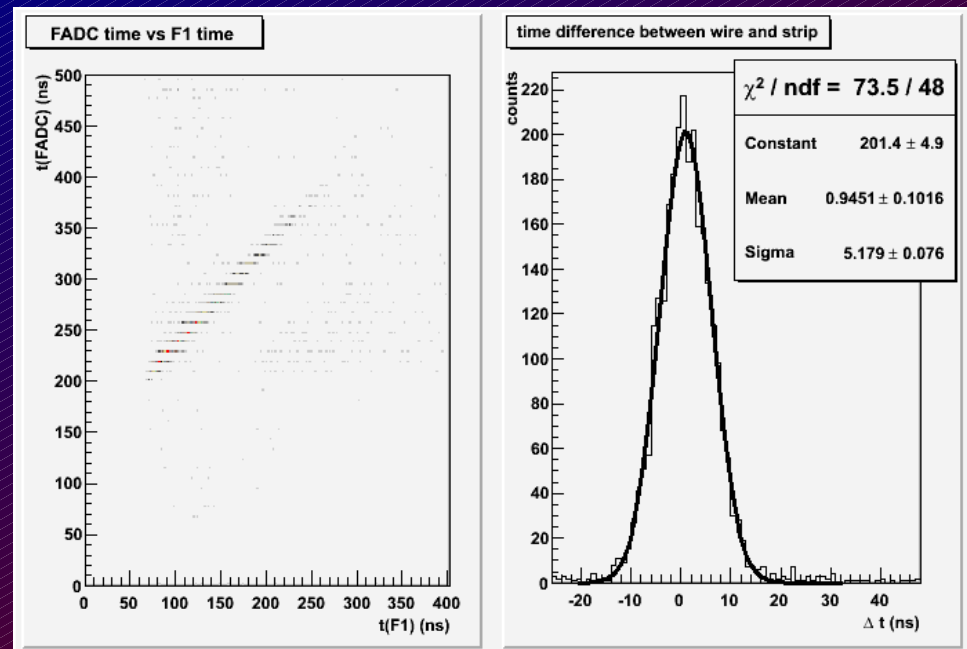
GlueX Electronics Meeting, April 6-7, 2006.

# Simple timing algorithm

Method 1: Leading edge technique.

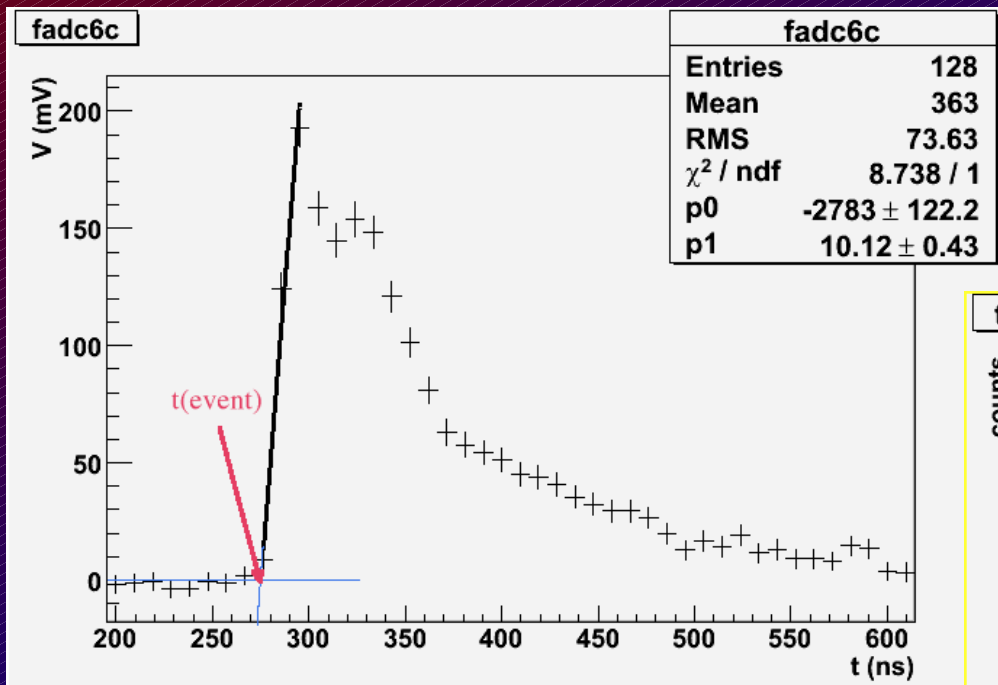
- Time at bin where data exceeds some threshold
- $\sigma_t = \Delta t / \sqrt{12} = 2.75 \text{ ns @ } 105 \text{ MS/s}$ ,  $\sigma_t = 4.44 \text{ ns @ } 65 \text{ MS/s}$
- Assuming drift velocity of  $50 \mu\text{m/ns}$ :  $\sigma_x = 137 \mu\text{m @ } 105 \text{ MS/s}$   
 $\sigma_x = 222 \mu\text{m @ } 65 \text{ MS/s}$
- Measured avalanche timing using leading-edge discriminators and F1 TDCs on the anode wires
- Compared this time with the time deduced from cathode strip with largest signal.

$V_{\text{anode}} = +1750 \text{ V}$   
20 mV CAMAC threshold  
5 mV software threshold  
 $n_{\text{wire}} = 1$

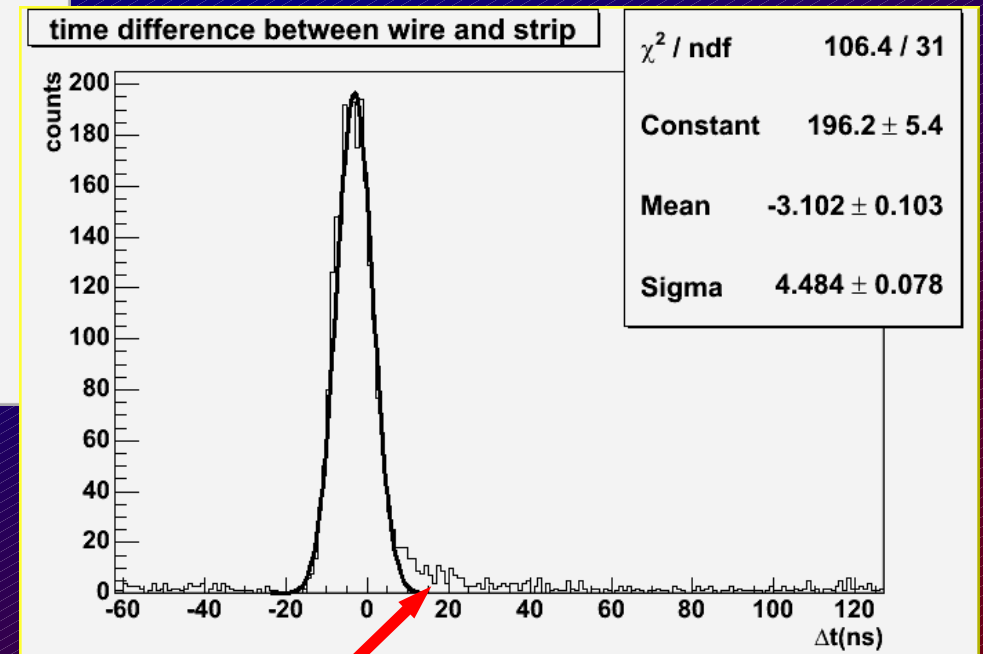


# Extraction of time II

Method 2: Linear extrapolation to intersection with background



Measurably narrower than Method 1 ...

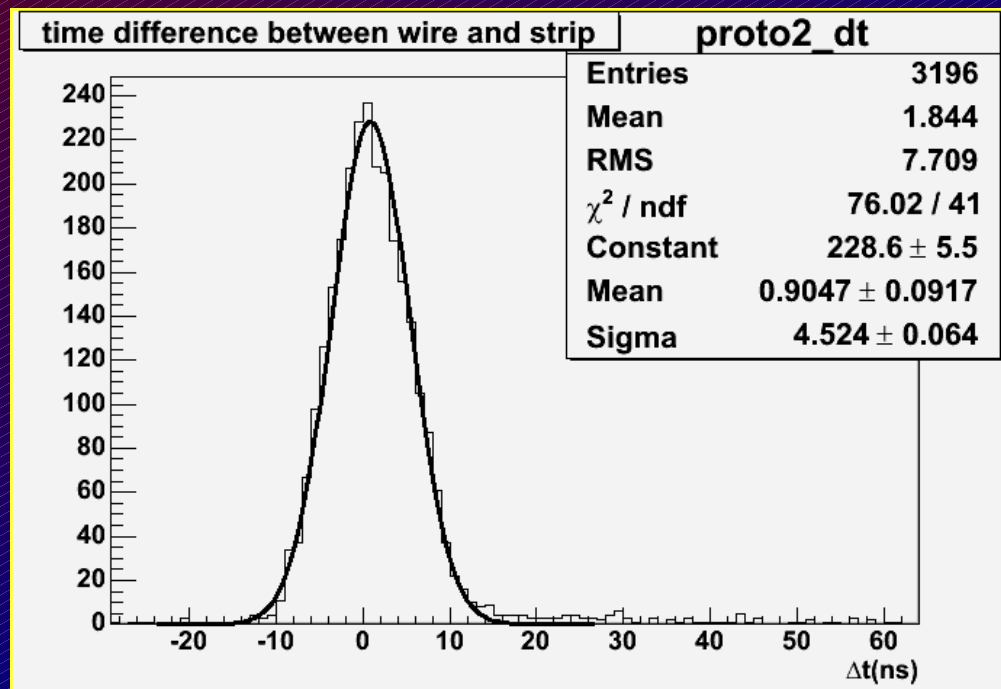


Use three samples, starting with the sample that exceeds some threshold (in this case 5 mV)

Asymmetric tail...

# More on linear extrapolation method

- Choice of first sample is important – get better results starting with sample *before* sample that exceeds threshold



$V_a = +1750 \text{ V}$ ,

Software threshold = 5 mV

Recall  $\sigma(\Delta t) = 5.18 \text{ ns}$  for one-sample method

→ 0.66 ns difference...

- Can we do better with a more realistic model for the pulse?



# Model for Pulse Shape (I)

Signal induced on wire seeing avalanche:

$$i(t) = \begin{cases} -q_a \frac{C}{4\pi\epsilon_0} \frac{1}{t+t_0} & \text{for } t \geq 0 \\ 0 & \text{for } t < 0 \end{cases}$$

(Corresponding cathode signals:)

$$i_c(\lambda, t) = \frac{q_c(\lambda)}{t+t_0} \text{ for } t \geq 0,$$

Model for preamp response function = single pole in s-space, exponential in t:

$$h(t) = \frac{-R_F}{\tau} e^{-t/\tau}, \text{ where } R_F \text{ is the preamp gain in mV/ } \mu\text{A}$$

Convolution:

$$V(t) = \int_0^t i(t')h(t-t')dt'.$$

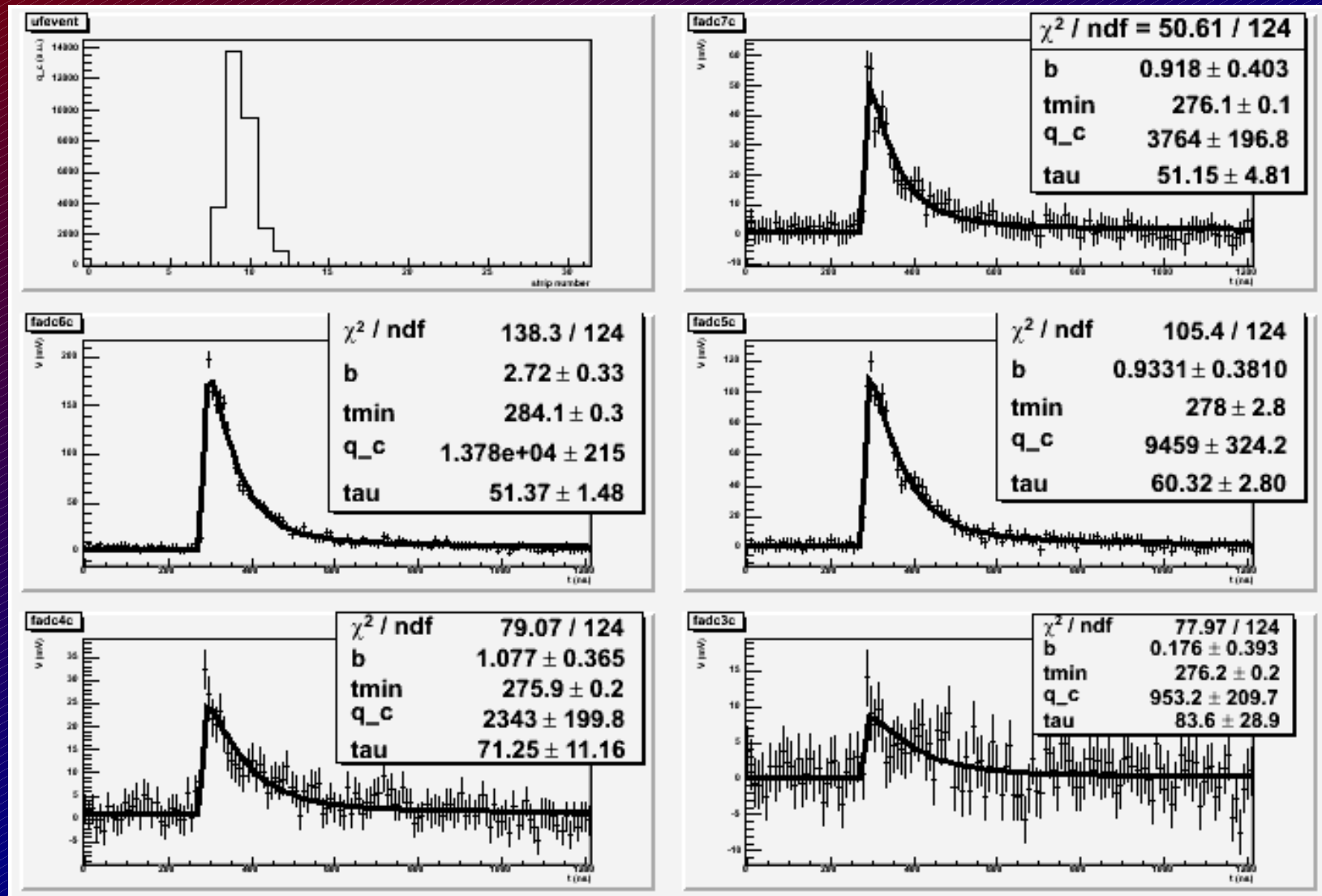
Result:

$$V(t) = \frac{q_a C R_F}{4\pi\epsilon_0 \tau} e^{-(t+t_0)/\tau} \left[ Ei\left(\frac{t+t_0}{\tau}\right) - Ei\left(\frac{t_0}{\tau}\right) \right] \text{ for } t \geq 0.$$

Exponential integral:

$$Ei(x) \equiv \int_{-\infty}^x \frac{e^z}{z} dz.$$

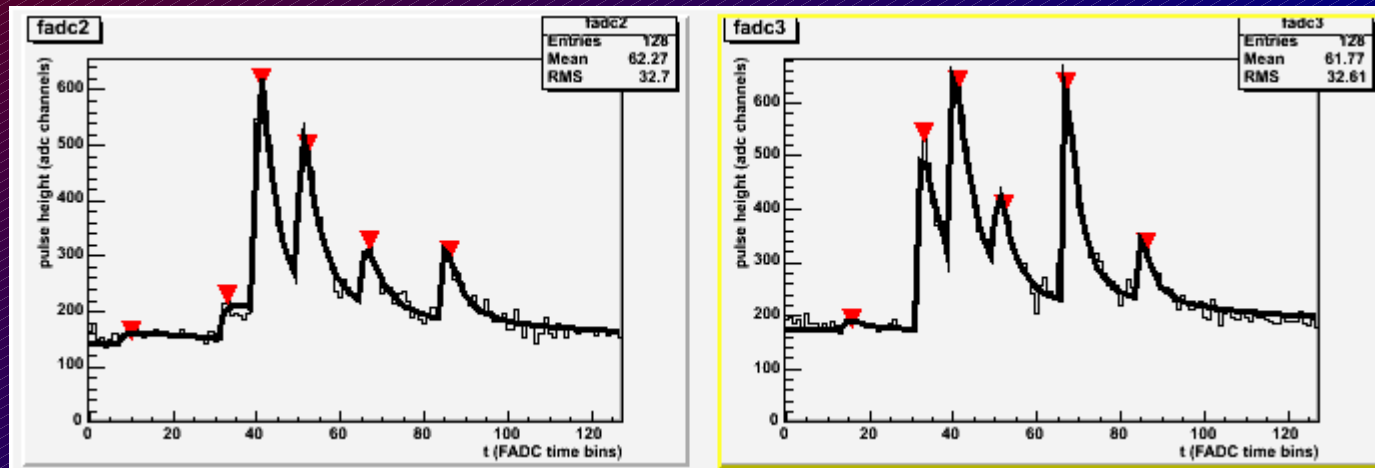
# Sample Event with pulse-shape fits



Shape well-described but need to fix  $\tau$  (should not vary from event to event)

# Multiple Pulsing

Sample signals on cathode strips at 1770 V anode voltage:



The problem worsens (becomes more frequent) as the high voltage is increased

- Peak-finding and pulse-fitting algorithm may be able to sort out the mess, but...
- Data suggests need to add quencher to gas to prevent secondary avalanches due to emission from cathode planes

# Newton-Raphson Method II

- Goal: use small number of samples with a good model for the shape of the leading edge to extract the time
- Time constant  $\tau$  should not change from event to event  $\rightarrow$  keep fixed.
- System of non-linear equations in 2 unknowns:  $\{t_{min}, q_c\}$

$$F_i = V_i - |V(\lambda, t_i; t_{min}, q_c)| = 0,$$

- Taylor expansion:

$$F_i(\vec{x} + \delta\vec{x}) = F_i(\vec{x}) + \sum_j \frac{\partial F_i}{\partial x_j} \delta x_j + \mathcal{O}(\delta\vec{x}^2),$$

- Estimate for correction:

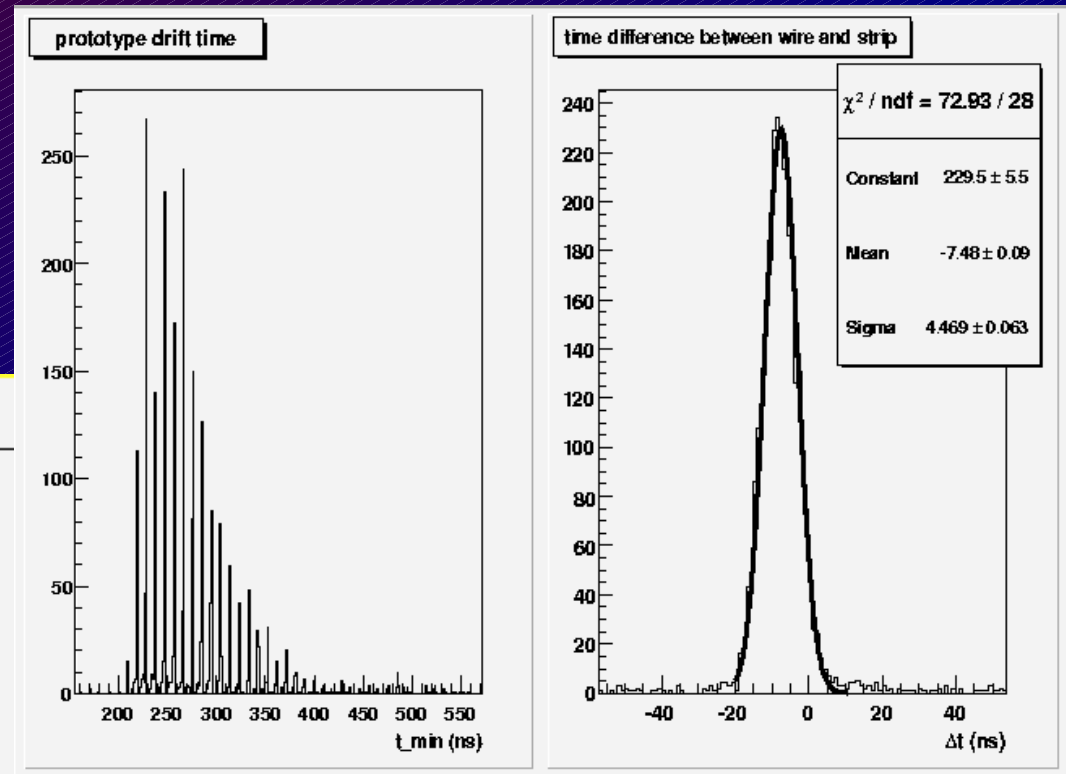
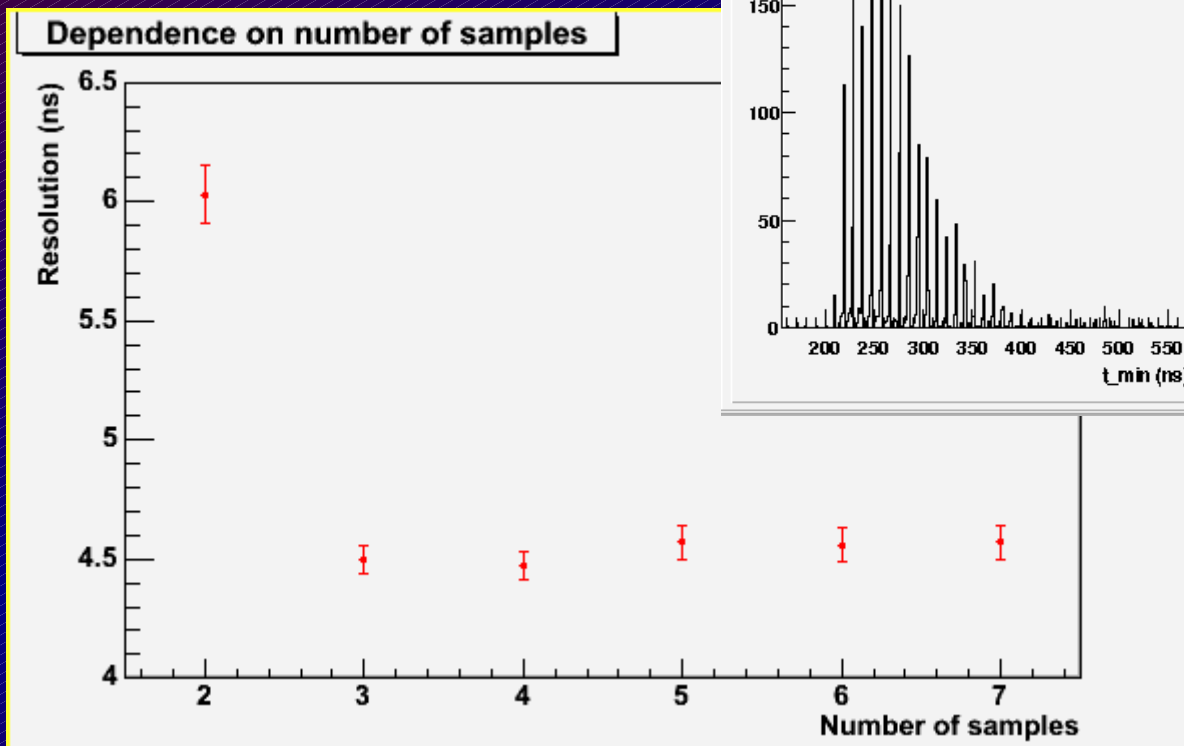
$$\delta\vec{x} = - (J^T J)^{-1} J^T \vec{F},$$
$$J_{ij} \equiv \frac{\partial F_i}{\partial x_j}.$$

- Iterate until  $\sum_j |\delta x_j| < \delta x_{min} = 0.0001$  or  $\sum_i |F_i| < F_{min} = 0.0001$ .

# Results for pulse shape model I

For N(Samples)=4:  $\sigma(\Delta t) = 4.47$  ns

$V_a = +1750$  V,  
Software threshold = 5 mV



The N=4 result is the same as for the linear extrapolation method...

# Improved Model for Pulse Shape

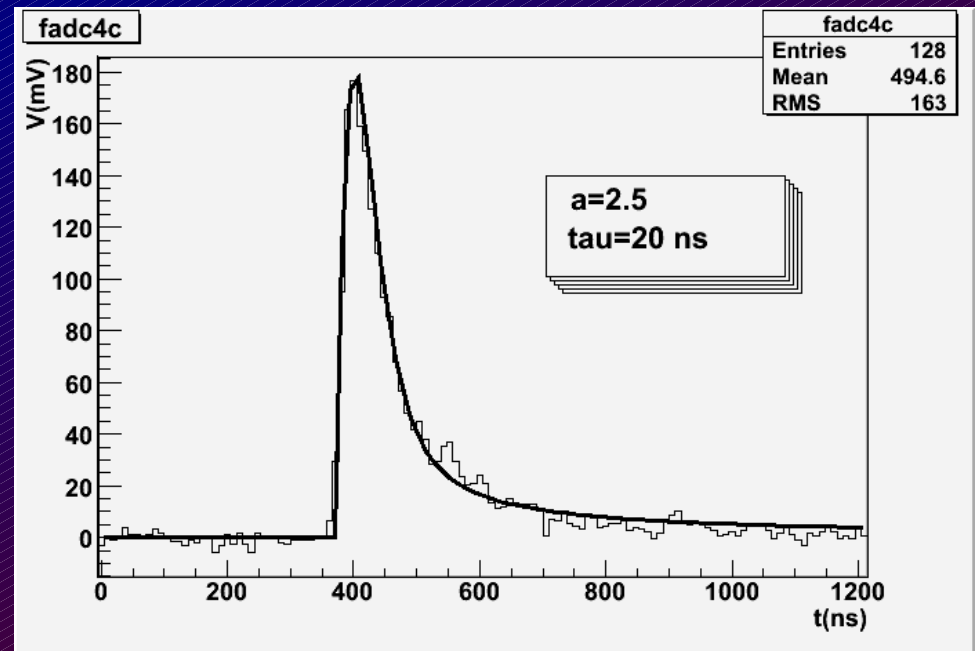
- Revised transfer function:

$$h(t) = -\frac{R_F}{\tau} e^{-t/\tau} \left( 1 + a \frac{t}{\tau} \right) \quad a=0 \text{ corresponds to previous model}$$

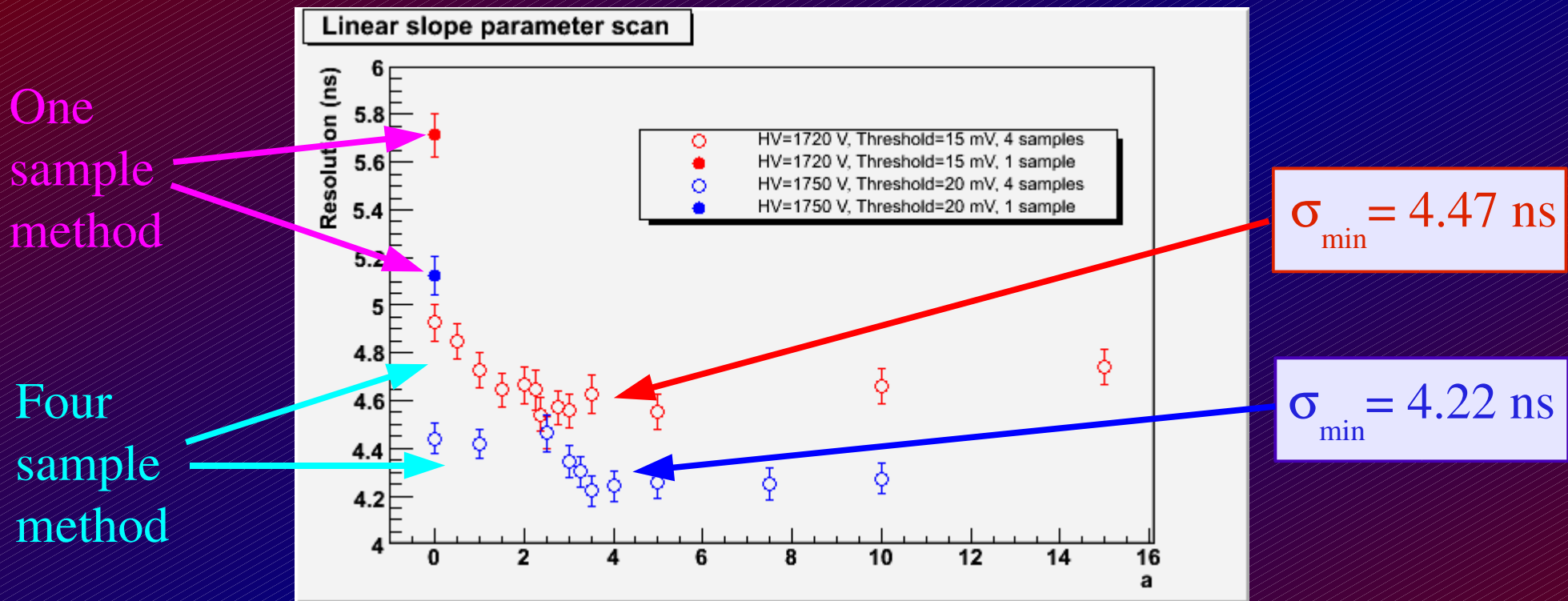
- Result of convolution:

$$V(t) = -\frac{qR_F}{\tau} \left[ e^{-(t+t_0)/\tau} \left( Ei \left( \frac{t+t_0}{\tau} \right) - Ei \left( \frac{t_0}{\tau} \right) \right) \left( 1 + a \frac{t+t_0}{\tau} \right) - a \left( 1 - e^{-t/\tau} \right) \right]$$

Sample cathode pulse,  
 $V_a = +1720 \text{ V}$



# Results for Pulse Shape Model II



- Effect of tuning  $a$  larger for smaller  $V_a$
- For  $V_a=1750$ ,  $\sim 250$  ps improvement relative to  $a=0$   
 $\rightarrow \sim 1$  ns improvement relative to one-sample method.

# Summary

- Simple one sample method gives worst timing results – more samples in leading edge needed
- Linear extrapolation and pulse shape model I give equivalent results for  $V_a = 1750 \text{ V}$
- Best results obtained for pulse shape model II after tuning the  $a$  parameter.