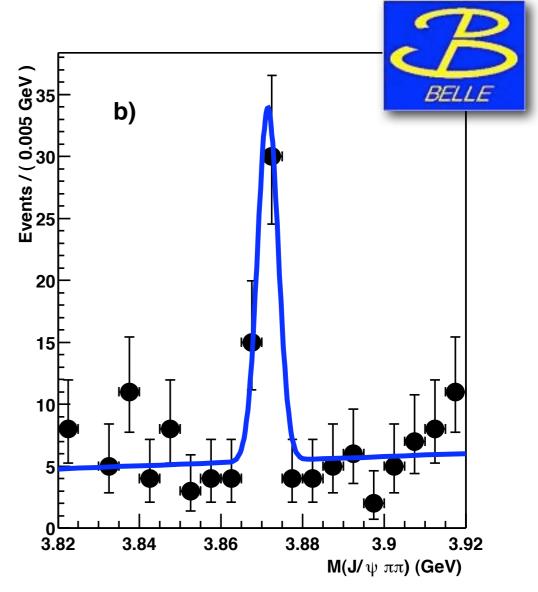
Analysis: What are the key observables and how do we make measurements?

GlueX Grad Student Workshop May 13, 2010

Matt Shepherd Indiana University

Spectroscopy Tools

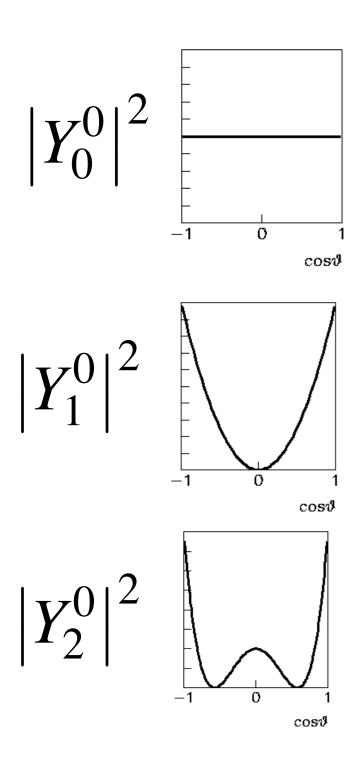
- Detector measures four-momenta of particles
- Many discoveries made by plotting invariant mass and looking for peaks ("bump hunting")
 - works best for narrow peaks (~10 MeV)
- GlueX needs to measure
 - mass and width of broad (~200 MeV) resonances
 - quantum numbers of resonances
- Need more than just magnitude of fourmomentum
 - angular distributions also relevant!

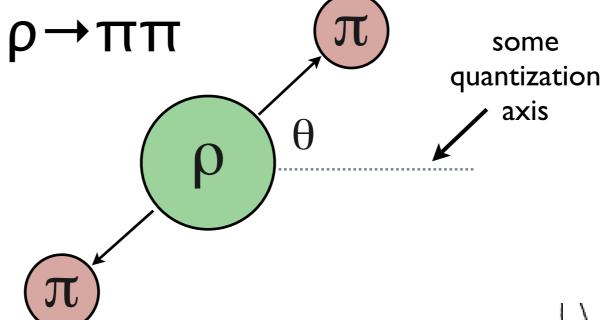


PRL 91, 262001 (2003)

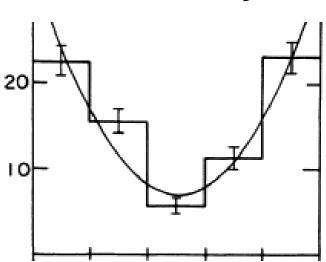


An Example: Measuring Spin





Pions are spinless so spin of ρ is carried in the orbital angular momentum of the two pions.



From data

conclude J = I

VOLUME 8, NUMBER 2

PHYSICAL REVIEW LETTERS

JANUARY 15, 1962

DIFFERENTIAL π - π CROSS SECTIONS: EVIDENCE FOR THE SPIN OF THE ρ MESON*

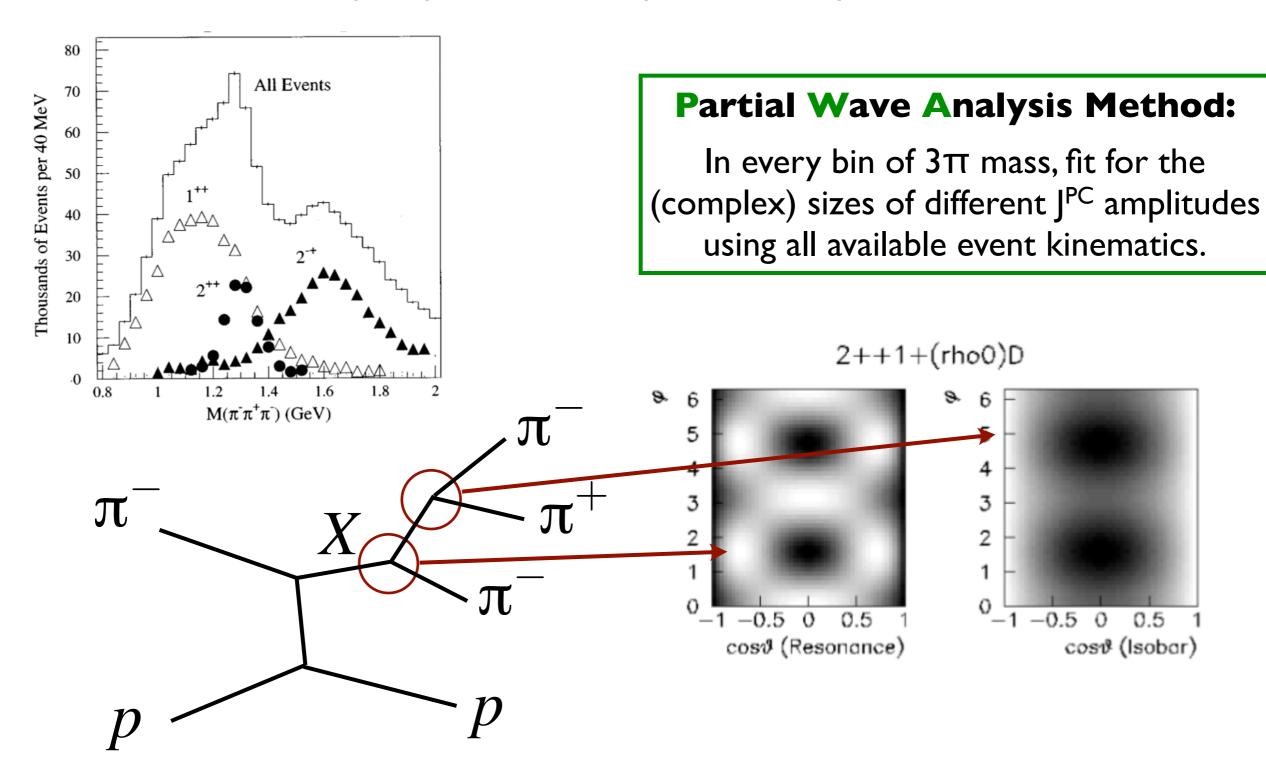
D. Duane Carmony[†] and Remy T. Van de Walle[‡]
Lawrence Radiation Laboratory, University of California, Berkeley, California
(Received November 6, 1961; revised manuscript received December 27, 1961)



Bloomington

A Modern Example

from pion production: $\pi^-p \to \pi^-\pi^-\pi^+p$ at 18 GeV/c



Amplitude Analysis

- historically called partial wave analysis (PWA), but we're not dealing really with "partial waves" anymore
- needs two very different but rather complicated ingredients
 - <u>Experimental/Technical</u>: multidimensional unbinned likelihood fit that correctly deals with detector acceptance
 - Theoretical: a physics model with free parameters that describes the experimental data
- What follows will be a brief introduction to this technique
 - warning: some technical details have been glossed over
 - hopefully there is enough detail to be useful
 - ask questions!



Maximum Likelihood

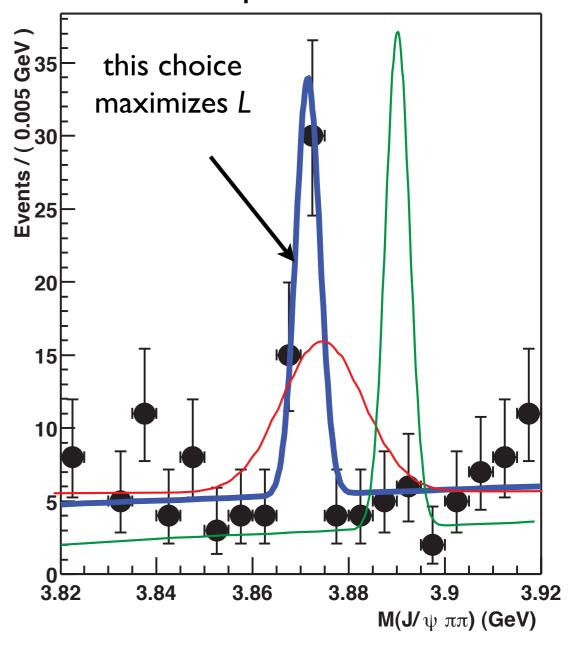
- Amplitude analysis is built around the (extended) maximum likelihood method
- Start with a model that contains free parameters (θ) and predicts the probability of having an event with a particular set of kinematic variables x (angles, invariant mass, etc.)

$$\mathcal{P}(\vec{x}; \vec{\theta})$$

 Vary the free parameters to maximize the probability for the entire data set

$$\mathcal{L} = \prod_{i=1}^{N_{ ext{events}}} \mathcal{P}(\vec{x}_i; \vec{ heta})$$

Example: ID in x

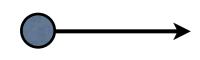


Experiment Application

Step 2: For each particle record location *x* where it was detected

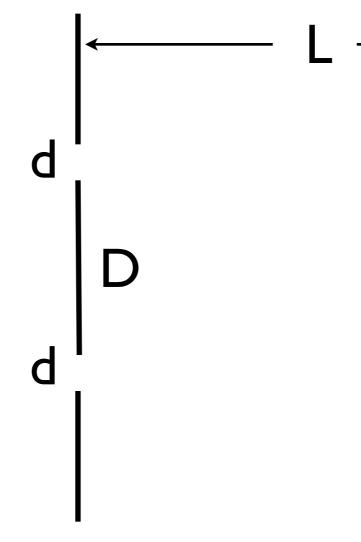
X

Step I: Shoot particles at slits



Probe
Beam of Particles
wavelength λ

Goal: determine the values of d and D



Physical System Under Study
Two Slits: width d, separation D

Detector

Measures location x_i
for each arriving particle



The Fit Procedure

 Our "theoretical model" that parametrizes the intensity of the particles in the detector is given by

$$I(x) = I_0 \left(\frac{\sin(d\pi x/\lambda L)}{d\pi x/\lambda L} \right)^2 \cos^2(2D\pi x/\lambda L)$$

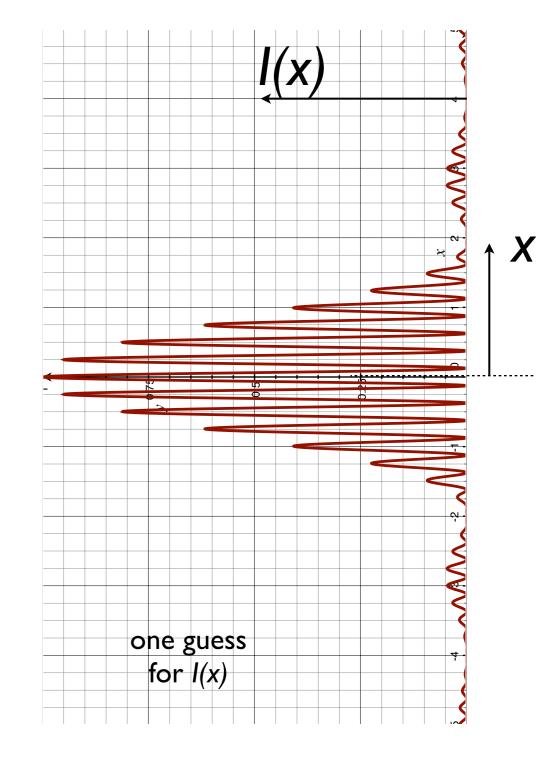
- Start with a guess for values for d and D
- Convert I(x) into a properly normalized PDF -- multiple techniques are available for evaluating the integral

$$\mathcal{P}(x) = \frac{I(x)}{\int_{x_{\min}}^{x_{\max}} I(x) dx}$$

Compute the likelihood by taking the product over all detected events

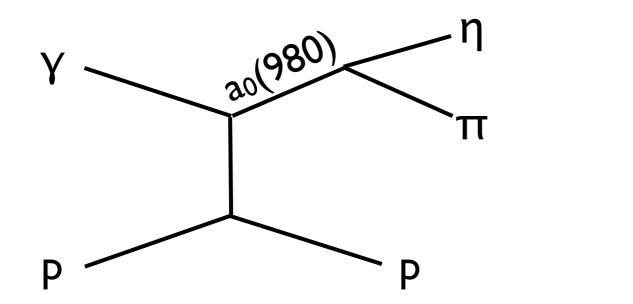
$$\mathcal{L} = \prod_{i=1}^{N} \mathcal{P}(x_i)$$

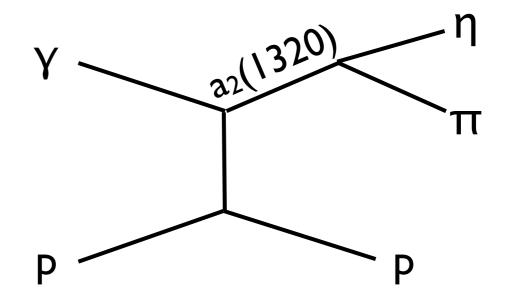
 Iterate with a new choice of d and D until the likelihood is maximized



Connecting to GlueX

• Suppose we have $\gamma p \rightarrow \eta \pi^0 p$, we can draw two (of many) possible diagrams





- Each of these can be related to an independent quantum mechanical amplitude
- Given any single event we do not know which process occurred -- they are indistinguishable

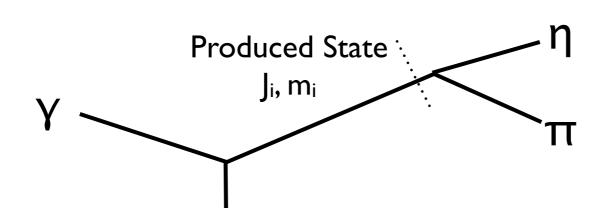
Amplitude Structure

decay amplitude

production amplitude

V_i unknown complex fit parameter

magnitude and phase of amplitude



 $A_i(\vec{x})$ complex function of
the final state observables, \vec{x} is a location in multi-body
phase space

"known"

$$A_i(\theta_{GJ}, \phi_{GJ}) \propto D_{m_i,0}^{J_i}(\theta_{GJ}, \phi_{GJ}, 0)$$

I is intensity:
number of
events per unit
phase space

$$I(\vec{x}) = \frac{dN}{d\vec{x}} = \left| \sum_{\alpha}^{N_{\text{amps}}} V_{\alpha} A_{\alpha}(\vec{x}) \right|^{2} = \sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^{*} A_{\alpha}(\vec{x}) A_{\beta}(\vec{x})^{*}$$

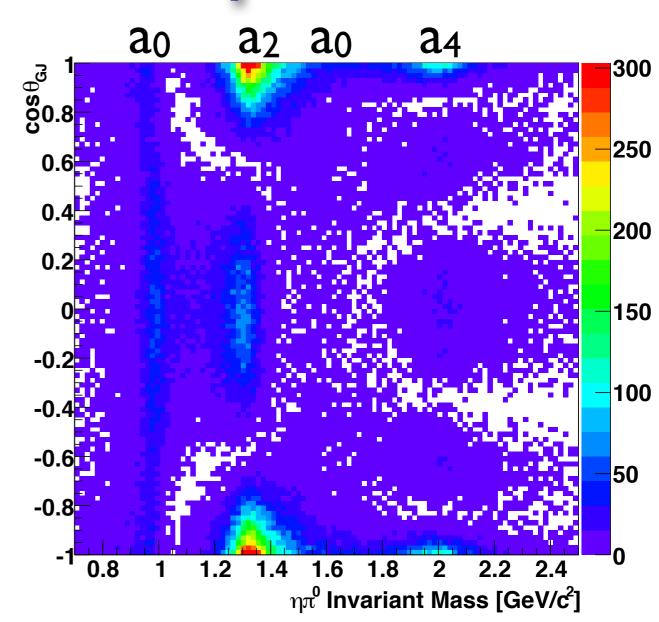
Incorporating Mass Dependence

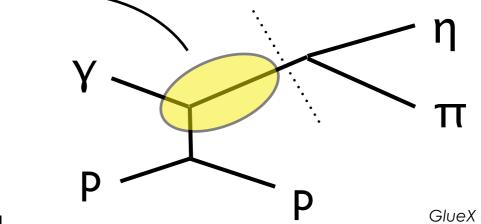
- For $\gamma p \rightarrow \eta \pi^0 p$ the spin of the $\eta \pi$ appears in just one variable related to the angle between the η (or π^0) and beam
- We can divide data into bins of $M(\eta\pi)$ and then do a fit in each bin of $M(\eta\pi)$ where we include 3 amplitudes corresponding to L=0, 2, and 4 in the $\eta\pi$ system
- We can then plot the fitted (complex) values of V for each of the three amplitudes as a function of $M(\eta \pi)$
- For a single resonance with mass M and width Γ, expect V to trace out the product of the production vertex and the Breit-Wigner propagator of the resonance

$$V(s) = \frac{V_0}{s - M^2 + iM\Gamma}$$

s: invariant mass squared of $\eta\pi$

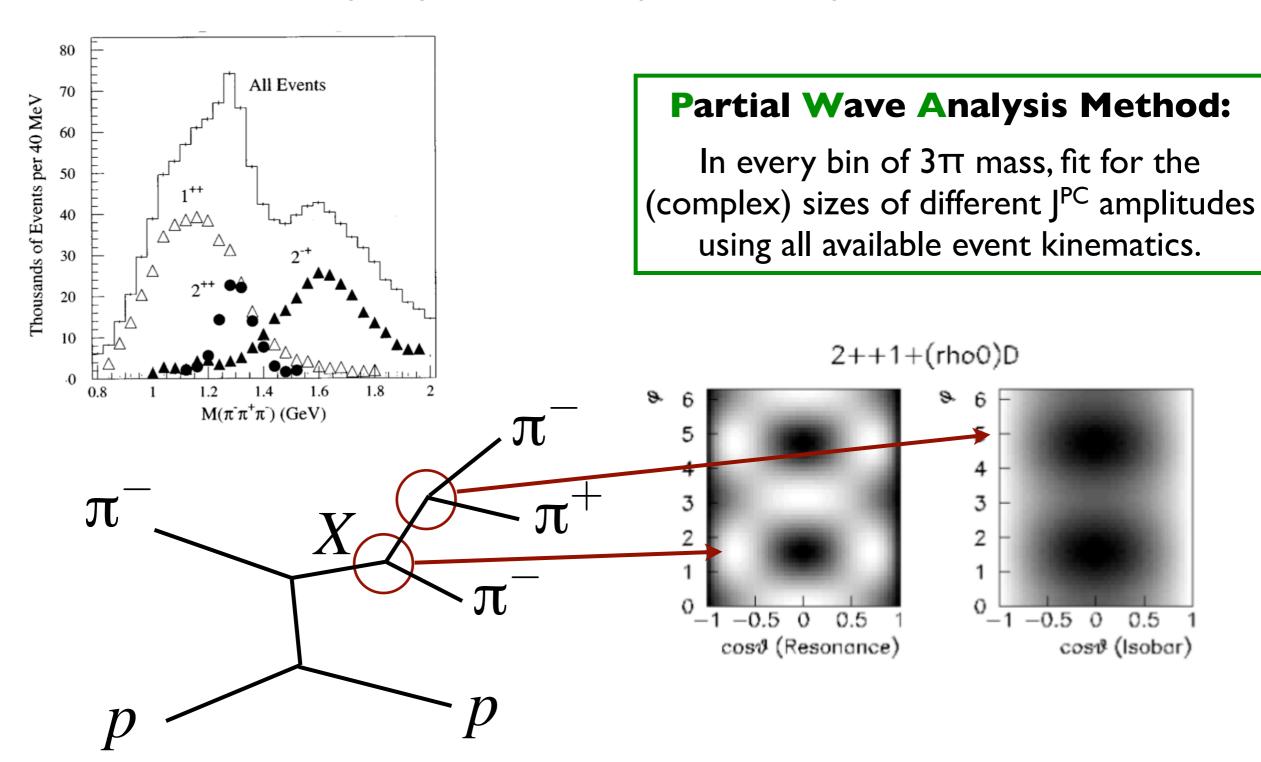






A Modern Example

from pion production: $\pi^-p \to \pi^-\pi^-\pi^+p$ at 18 GeV/c



Implementation Details

We fold in Poisson statistics and a detection efficiency η to arrive at the final likelihood expression for N observed events

$$\mathcal{L} = \frac{e^{-\mu}\mu^N}{N!} \prod_{i=1}^N \frac{\eta(\vec{x}_i)I(\vec{x}_i;\vec{V})}{\int \eta(\vec{x})I(\vec{x};\vec{V})d\vec{x}} \qquad \qquad \mu = \int \eta(\vec{x})I(\vec{x};\vec{V})d\vec{x}$$

fit-predicted

Removing constant terms, the log of the likelihood, which must be computed at every fit iteration, reduces to

$$\ln \mathcal{L} = \left(\sum_{i=1}^{N} \ln \left(\sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^* \underline{A_{\alpha}(\vec{x}_i) A_{\beta}(\vec{x}_i)^*}\right) - \sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^* \int \eta(\vec{x}) \underline{A_{\alpha}(\vec{x}) A_{\beta}(\vec{x})^*} d\vec{x}\right)$$

Sum of N logs each with N_{amps}^2 terms drives fit time

Model appears in A; if it does not contain parameters, A can be computed and cached for every event

Integrals are computed using Monte Carlo integration: needs η from high-statistics detector Monte Carlo sample; answer never changes if A are fixed

To fully explore the model space, we need to be able to parameterize A. This eliminates computational optimizations that have been historically used.

Parallel Computing

 This type of problem is perfect for parallel computing since all of the large sums over can be done in parts

$$\ln \mathcal{L} = \sum_{i=1}^{N} \ln \left(\sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^* A_{\alpha}(\vec{x}_i) A_{\beta}(\vec{x}_i)^* \right) - \sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^* \int \eta(\vec{x}) A_{\alpha}(\vec{x}) A_{\beta}(\vec{x})^* d\vec{x}$$

$$\int \eta(\vec{x}) A_{\alpha}(\vec{x}) A_{\beta}(\vec{x})^* d\vec{x} \to \frac{1}{N_{\text{MC}}^{\text{gen}}} \sum_{i=1}^{N_{\text{MC}}^{\text{acc}}} A_{\alpha}(\vec{x}_i) A_{\beta}(\vec{x}_i)$$

- Initially each node needs a sub-collection of data or MC and an algorithm for computing the A
- With each fit iteration the node just needs to know the new values of the fit parameters and it returns its contribution to the log likelihood
- Excellent application for GPU computing: compute amplitudes in parallel for all events and then collect sum



Amplitude Analysis Recap

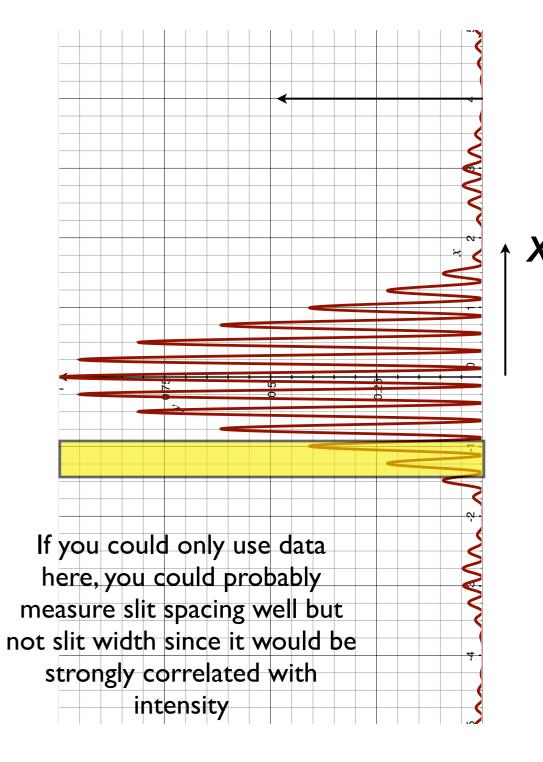
- The analysis technique for extracting masses, widths, and quantum numbers of broad resonances at GlueX
- Maximizes precision by doing a multi-dimensional unbinned fit: binning data and or integrating over variables always results in a loss of knowledge
- Requires a theoretical model with parameters, which is typically a sum of amplitudes with production coefficients as parameters
- Very compute intensive but can be parallelized, implementations exist for multi-core, multi-machine, and graphics processing applications

How can we go wrong?



Poor Acceptance

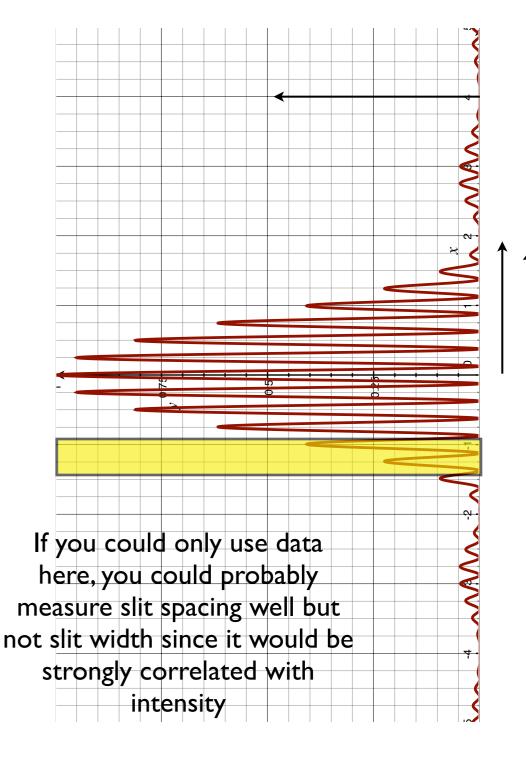
 Problem: the predicted intensity in the active region doesn't vary much when a parameter, e.g. d, is varied which leads to insensitivity in measuring d



Poor Acceptance

- Problem: the predicted intensity in the active region doesn't vary much when a parameter, e.g. d, is varied which leads to insensitivity in measuring d
- Test:
 - generate a simulated set of four-vectors that includes some physics process
 - propagate the four-vectors through the detector and reconstruction to produce simulated data
 - fit these simulated data to extract parameters of the underlying physics process

GlueX needs to be a high acceptance detector!





Poorly Understood Acceptance

- <u>Problem</u>: the acceptance function $\eta(\vec{x})$ used in the fit doesn't match the real detector acceptance, so the parameters of $I(\vec{x}; \vec{V})$ come out incorrect when the product $\eta(\vec{x})I(\vec{x}; \vec{V})$ is fit to data.
 - Acceptance appears in normalization integral, which is done numerically, by Monte Carlo techniques

$$\ln \mathcal{L} = \sum_{i=1}^{N} \ln \left(\sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^* A_{\alpha}(\vec{x}_i) A_{\beta}(\vec{x}_i)^* \right) - \sum_{\alpha,\beta}^{N_{\text{amps}}} V_{\alpha} V_{\beta}^* \int \eta(\vec{x}) A_{\alpha}(\vec{x}) A_{\beta}(\vec{x})^* d\vec{x}$$

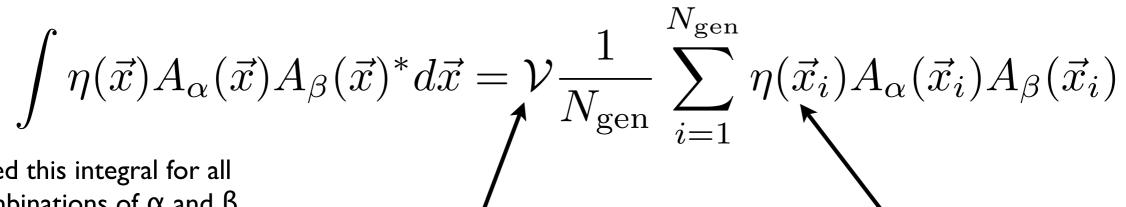
• Monte Carlo integration example in one dimension: randomly generate for N different x_i that uniformly populate $[x_{min},x_{max}]$

$$\int_{x_{\min}}^{x_{\max}} f(x)dx = (x_{\min} - x_{\max})\langle f(x)\rangle \quad \text{and} \quad \langle f(x)\rangle = \frac{1}{N} \sum_{i=1}^{N} f(x_i)$$



Poorly Understood Acceptance

 The fit relies on integrals which can be calculated by using Monte Carlo physics events that are generated uniformly over the volume of multidimensional phase space in which the fit is done



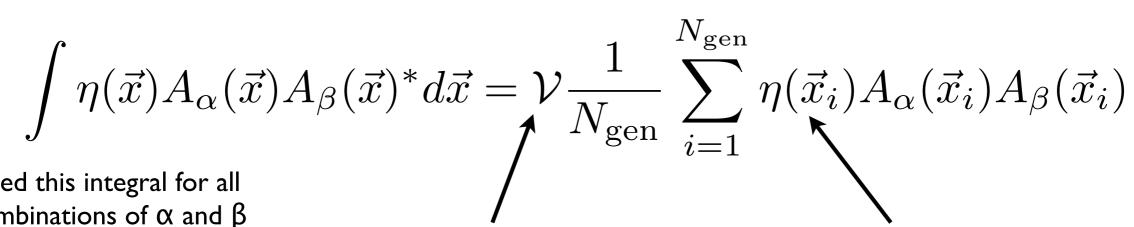
need this integral for all combinations of α and β (amplitude indices)

volume of phase space, adds constant term in ln L so it can be ignored

simulated acceptance enters here: $\eta=1$ if Monte Carlo event is detected by detector and selected for analysis, $\eta=0$ otherwise

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<u>Test</u>: Generate a simulated data set with some known physics process. Artificially "break" the detector simulation (introduce holes, degrade efficiencies, etc.) in the sample of phase space Monte Carlo used to compute the integrals above. Are the results of the fit robust?

Incorrect Physics Model

- Ideally the parameters of the fit correspond to quantities that have some fundamental physical interpretation, e.g., the masses, widths, and production rates of resonances
- Remember the fitting procedure only returns the most likely values of the parameters given some model -- it is up to us to supply the correct model for the data. (Goodness of fit is not reflected in the statistical errors on parameters!)



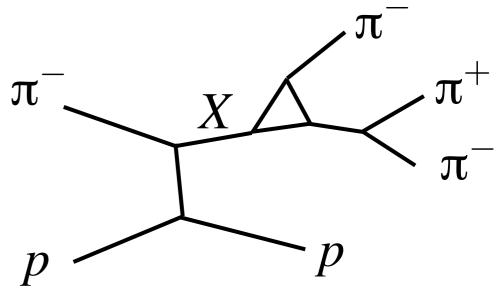
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- Experimental problem: backgrounds from other physics processes contaminate the final data sample -- this invalidates assumption of pure interfering amplitudes.
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 - We must demonstrate GlueX can cleanly reconstruct final states.
 - Our ability to extract small signals will be limited by how well we can minimize background or account for it in the fit.
- Theoretical problem: more complicated physics processes exist in reality, but not in the model.
 - Development of complex physics models was previously limited by lack of data to test them and computational resources to use them in the fit -- no longer true with GlueX (we hope!)





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 - Understand the algorithms -- are they correct and optimal?
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 - Understand the theoretical assumptions -- are they valid?
- Because of its incredible statistical precision, many GlueX analyses will likely become systematics limited -- we will really need analysis experts (you!) to overcome these limitations.
 - There are interesting problems in need of creative solutions that can be tackled right now using simulated data.

