

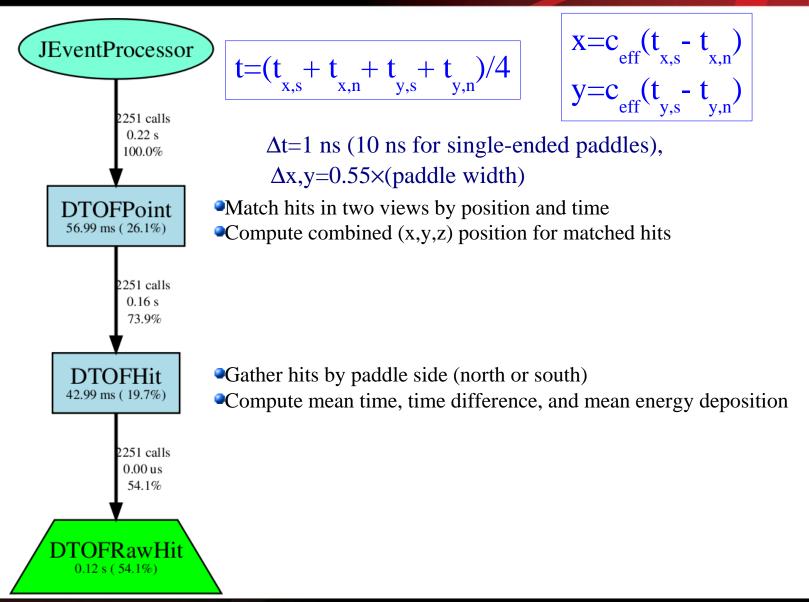
# **Time-of-Flight reconstruction**

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#### **Reconstruction chain**







### **More details**

•In *DTOFHit*, thresholds applied in software based on ADC values, but currently hits below the threshold are still kept... with many parameters ( $t_{mean}$ , etc.) set to NaN

•Code also computes corrected energy deposition in the bars:

 $E_{n} = E_{n,ADC} \cdot e^{(\frac{L}{2} - x)/a}$   $E_{s} = E_{s,ADC} \cdot e^{(\frac{L}{2} + x)/a}$   $E = \frac{E_{s} + E_{n}}{2}$  L=length of paddle a = attenuation length  $I=\frac{E_{s} + E_{n}}{2}$   $I=\frac{DTOFHit}{(geometric average in DTOFPoint)}$ 

•In *DTOFPoint*,  $E \rightarrow (E_x + E_y)/2$  (except for matches involving single-ended paddles)

In *DTOFPoint*, for intersections involving single-ended paddles:
Mean time from matched double-ended paddle is used for *t*Center of single-ended paddle used for coordinate (x or y)





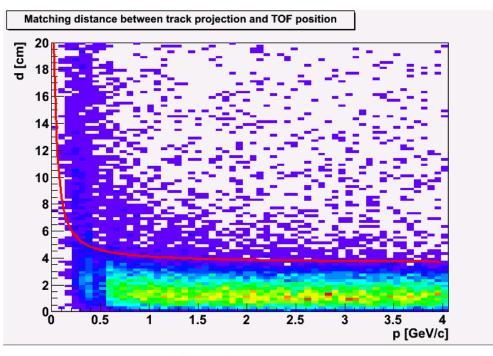
# **Matching between tracks and TOF**

•The helper class DParticleID provides many useful utilities related to particle ID

•For matching to the TOF wall, it provides *DParticleID::MatchToTOF* 

•Match using distance d between track projection to the TOF z-plane and (x,y) position reported by **DTOFPoint** 

•Momentum-dependent cut: d<3.624+0.488/p



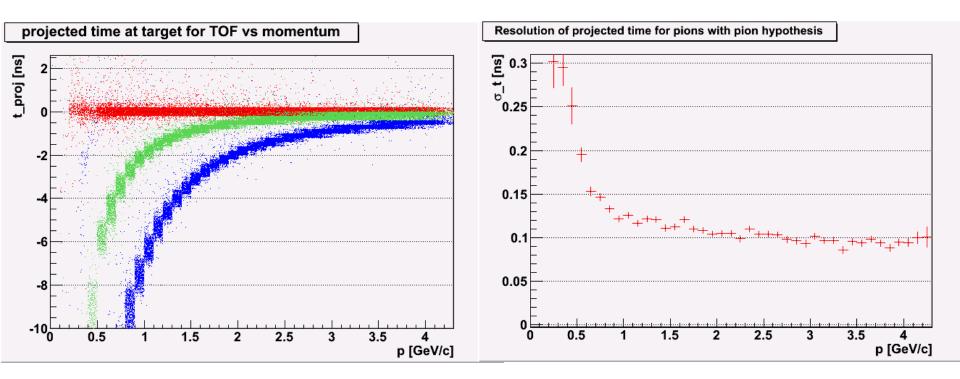




#### Projected time at the "vertex"

π<sup>+</sup>'s thrown from center of target, θ < 11°</li>
 Thrown start time = 0
 TOF resolution per PMT = 100 ps
 t = t - t

 $\bullet t_{\rm proj} = t_{\rm TOF} - t_{\rm flight, \ from \ tracking}$ 







# **Missing pieces**

No time-walk correction algorithm implemented
Cases where track crosses two adjacent paddles in a view not explicitly treated



